

Towards JEDI@COSY: systematic studies of spin dynamics in preparation for the EDM searches

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Outline

- Exploring the COSY ring for Electric Dipole Moment (EDM) studies (JEDI - Jülich Electric Dipole moment Investigations)
- Imperfection background to EDM spin precession
- Mapping the spin tune with static solenoids
- Summary



Cooler Synchrotron COSY in Jülich





Spin Motion in Storage Ring

• Thomas BMT eqn. for the Magnetic Dipole Moment (MDM)

$$\frac{d\vec{S}}{dt} = \vec{S} \times \vec{\Omega}_{MDM}$$
$$\vec{\Pi}_{MDM} = \frac{q}{m} \left(G\vec{B} - \left(G - \frac{1}{\gamma^2 - 1} \right) \frac{\vec{\beta} \times \vec{E}}{c} - \frac{G\gamma}{\gamma + 1} \vec{\beta} (\vec{\beta} \cdot \vec{B}) \right)$$

<u>Spintune</u> \coloneqq Number of spin turns relative to particle turns, for the ideal pure magnetic ring like COSY:

$$v_{s} \coloneqq \frac{\left|\vec{\Omega}_{MDM}\right|}{\omega_{rev}} = \frac{\frac{q}{m}GB}{\frac{q}{m\gamma}B} = \gamma G$$



Spin Precession by EDM in Pure Magnetic Ring



of the deuteron and proton Electric Dipole Moment (EDM) at COSY

• JEDI looks forward to the RF E-field induced EDM rotation without excitation of the coherent betatron oscillations. Example: RF Wien-Filter, EDM signal comes from ring

«RF Wien filter in an electric dipole moment storage ring: The "partially frozen spin" effect». William M. Morse, Yuri F. Orlov, Yannis K. Semertzidis. Phys.Rev.ST Accel.Beams 16 (2013) 11, 114001

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 \vec{n}_{co}

Cz

 $Z \checkmark$

Imperfection In-plane Fields

- A current task for JEDI: exploring the EDM dynamics and systematic limitations of the EDM searches at all magnetic rings
- Misalignment of any magnetic elements produces the in-plane imperfection magnetic fields
- Imperfection spin kicks perturb \vec{n}_{co} :

 $\vec{n}_{co} = \left(\vec{e}_x c_1 + \vec{e}_y c_2 + \vec{e}_z c_3\right)$

- The nonvanishing c_1 and c_3 generate a background to the EDM-signal of the ideal imperfection-free case $c_1 = \sin \xi$, $c_3 = 0$
- The challenge is to control background (for example with the accuracy $c_1 \sim 10^{-6} rad$ would amount to sensitivity for $d = 10^{-20} e \cdot cm$)

 C_1

X



EDDA Polarimeter

• Left-Right asymmetry \Rightarrow vertical polarization $P_V \propto \epsilon_{ver} = \frac{N_l - N_r}{N_l + N_r}$



• Up-Down asymmetry \Rightarrow horizontal polarization $P_H \propto \epsilon_{hor} = \frac{N_{up} - N_{dn}}{N_{up} + N_{dn}}$





Spin Tune Measurement

- Spin vector precesses with $f_{\text{Spin}} = v_s f_{rev}$ in the horizontal plane around spin closed orbit
- Asymmetry is given by:

$$\epsilon_{hor}(t) = \frac{N_{up} - N_{dn}}{N_{up} + N_{dn}} \approx AP(t)\sin(2\pi\nu_s f_{rev}t + \phi)$$

- What do we expect? (Deuterons, p = 0.97 GeV/c) $v_s \approx 0.16$, $f_{rev} = 750$ kHz
- Spin precession frequency: $v_s \cdot f_{rev} \approx 120 \text{ kHz}$
- Special spin tune analysis software resolves v_s with an accuracy 10^{-8} in 1-second interval



Spin Tune Response to the Artificial Imperfections

 The spin tune is perturbed by small spin kicks ~a in the ring imperfection fields:

$$\nu_0 = G\gamma + O(a^2)$$

- The idea is to probe the in-plane imperfection fields by introducing well-known *artificial imperfections*.
- Apply artificial imperfections: spin kicks χ₁ and χ₂ by the compensation solenoids in e-coolers, located in both straight sections,

$$v_s = v_0 + O(c_3^2, (c_3^*)^2, \chi_1^2, \chi_2^2)$$

Measure the spin tune shift w.r.t. applied spin kicks, $\Delta v_s(\chi_1, \chi_2) = v_s(\chi_1, \chi_2) - v_0$





Measurement of Spin Tune Shift

• Spin tune shift registered in the data analysis:



The spin tune shift was observed at t = [20, 45] s

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The Spin Tune Mapping

Take multiple measurements with different χ_1 , χ_2 and build a spin tune map $\Delta \nu_s(\chi_1, \chi_2)$:



Spin tune shift w.r.t. the solenoid spin kicks, $\Delta v_s \sim \chi_1^2$, $\Delta v_s \sim \chi_2^2$

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The Spin Tune Mapping

• If the kicks are translated to:

$$y_{+} = \frac{1}{2}(\chi_{1} + \chi_{2})$$
 $y_{-} = \frac{1}{2}(\chi_{1} - \chi_{2})$

• then

$$\Delta v_s \propto -(y_- - a_-)^2$$
, $\Delta v_s \propto (y_+ - a_+)^2$

- The distributions of the data points in y_{\pm} dimension share common parabolic features : equal curvature and extremum a_{\pm}
- It is a sign that the solenoids work as anticipated:





Imperfection Strength



- Position of the saddle point measures projections of SCO, c_3 and c_3^*
- Strength of imperfection fields in the ring is at the level of $\approx 3 Tmm$
- For an ideal ring, the saddle point would be at $a_{\pm} = 0$



Summary

- The technique of spin tune measurement appears as a precision tool for the systematic analysis of the ring imperfections
- First high precision measurement of the imperfection fields at COSY



The ultimate goal of the JEDI: to understand the EDM dynamics in storage rings as a prerequsite to the construction of the dedicated storage ring for the EDM searches



More Details About Spin Tune Analysis





Fit Asymmetry to First Period



- 2. Mapping events
- Fit asymmetry to first period



Extract amplitude $A \propto Polarisation$



Find Correct Spin Tune

- Vary $T_{assumed}$ and repeat steps 1 to 3
- Plot extracted parameter A vs $v_{assumed}$
- 1. *T_{assumed}*

- 2. Mapping events
- Fit asymmetry to first period

- V max 0.15 0.10 0.05 0.10 0.05 0.160970 0.160975 0.160980 0.160985 0.160985 Vassumed
- v_{max} is correct spine tune in macroscopic time interval (2 s)
- $v_{max} = 0.160975 \pm 10^{-6}$



- c_3 is given after one of the solenoid, and c_3^* after another
- Model function:

$$\Phi = \cos \pi (\nu_0 + \Delta \nu_s (y_+, y_-)) - \cos \pi \nu_0 = \\ - \left[(E + \cos \pi \nu_0) \sin^2 \left(\frac{y_+}{2}\right) + \frac{1}{2} \sin \pi \nu_0 (c_3 + c_3^*) \sin y_+ + (E - \cos \pi \nu_0) \sin^2 \left(\frac{y_-}{2}\right) + \frac{1}{2} \sin \pi \nu_0 (c_3 - c_3^*) \sin y_- \right]$$

• for a guidance:

$$\Phi \simeq -\pi \Delta \nu_s \sin \pi \nu_0 \propto y_+^2, y_-^2$$

- $E \approx \cos \frac{\pi(\nu_1 \nu_2)}{2} \approx 1$ is related to the difference of horizontal spin phase advances in the arcs
- The theory tells



• The extremum of Φ is a saddle point at $y_+, y_- = O(c_3, c_3^*)$

• With solenoids only we are not sensitive to c_1 , c_1^*

• Once v_0 has been determined, only c_3 and c_3^* are the fit parameters