

ACCURATE POSITION CALIBRATION OF BEAM POSITION MONITORS IN STORAGE RINGS Beam-based alignment at COSY

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RNTHAACHE





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- Cooler Synchrotron COSY in Jülich
- Why is a calibration of beam position monitors needed?
- Method of beam-based alignment
- Measurements done up to now
- Measurements in the future



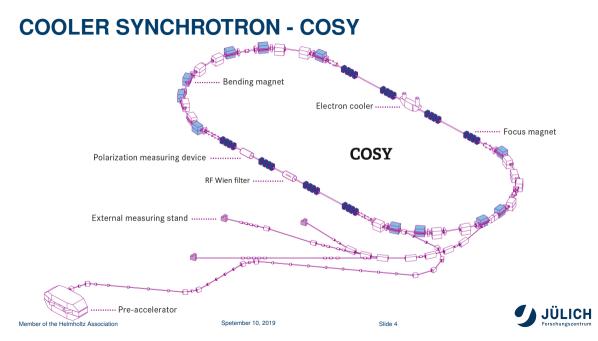


COOLER SYNCHROTRON - COSY

- 184 m circumference
- Polarized protons and deuterons
- 10⁹ to 10¹⁰ particles
- Electron cooling
- Spin manipulation
- Current JEDI experiment uses deuterons with p = 970 MeV c⁻¹
- JEDI collaboration measures the electric dipole moment of deuterons





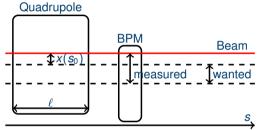


WHY IS A POSITION CALIBRATION NEEDED?

- Regular surveys of the accelerator make sure that the magnets are aligned properly
- Surveys use markers mounted on magnets as reference points
- Beam position monitors (BPMs) do not have those markers, thus exact positioning is not known precisely
- Want to have a good orbit with a small RMS for the electric dipole measurement
- Need method to measure the exact positioning of the BPM to have a well known orbit
 Beam-based alignment

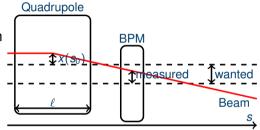


- Use beam to optimize the beam position
- Vary quadrupole strength
- Observe orbit change
- Try to minimize the orbit change



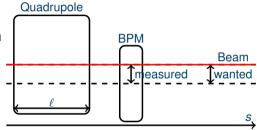


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How does the orbit change when varying the quadrupole strength?

$$\Delta x(s) = \frac{\Delta k \cdot x(s_0)I}{B\rho} \cdot \frac{1}{1 - k \frac{I\beta(s_0)}{2B\rho \tan \pi \nu}} \cdot \frac{\sqrt{\beta(s)}\sqrt{\beta(s_0)}}{2\sin \pi \nu} \cos[\phi(s) - \phi(s_0) - \pi \nu]$$

 Not possible to calculate x(s₀) due to lack of precise knowledge of all other parameters

$$f = rac{1}{N_{ ext{BPM}}}\sum_{i=1}^{N_{ ext{BPM}}} \left(x_i(+\Delta k) - x_i(-\Delta k)
ight)^2 \propto (oldsymbol{x(s_0)})^2$$

• By finding the minimum ($f \rightarrow 0$) the optimal beam position can be found



BEAM-BASED ALIGNMENT MEASUREMENT

Constraints and Procedure

- Constraints at COSY
 - Quadrupoles are powered in families of four
 - On the poles of 12 quadrupoles additional back-leg windings are mounted
 - The back-leg windings can be recabled to act as a quadrupole



BEAM-BASED ALIGNMENT MEASUREMENT

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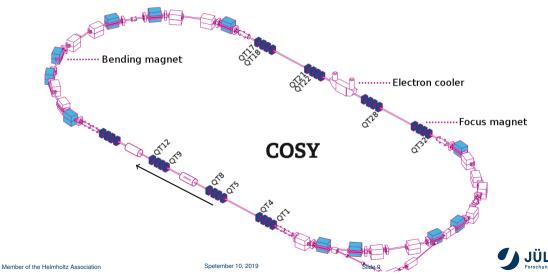
Procedure

- Effectively the strength of these quadrupoles can be varied
- Local bumps are applied at the positions of the quadrupoles
- Observing the effect on the orbit while varying the quadrupole strength



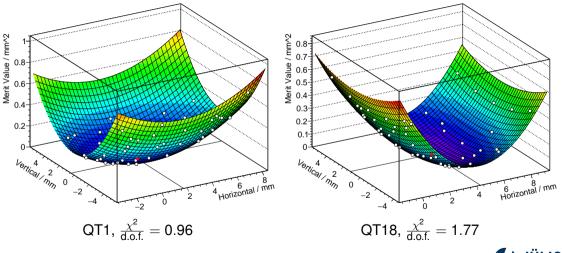
BEAM-BASED ALIGNMENT MEASUREMENT

Locations of the 12 quadrupoles



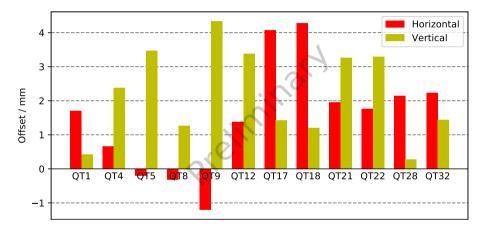
RESULTS

Examples for the fits





RESULTS





RESULTING BPM CALIBRATION

BPM name	Horizontal correction	Vertical correction
BPM02 (s = 10.4 m)	$(1.705\pm0.008)\text{mm}$	$(0.416\pm0.005)\text{mm}$
BPM06 (s = 29.5 m)	(1.371 ± 0.007) mm	(3.382 ± 0.011) mm
BPM18 (s = 100.2 m)	$(4.177\pm0.007)\text{mm}$	(1.308 \pm 0.005) mm
BPM19 (s = 110.1 m)	(1.868 ± 0.005) mm	(3.273 \pm 0.010) mm
BPM20 (s = 123.3 m)	(2.149 \pm 0.007) mm	(0.281 \pm 0.007) mm
BPM21 (s = 133.2 m)	(2.232 \pm 0.008) mm	(1.430 \pm 0.006) mm

Resulting orbit improvement from $RMS_y = 1.21 \text{ mm}$ to 1.01 mm with only 20% of the BPMs calibrated.



MEASUREMENT FOR ALL QUADRUPOLES

- New power supplies bought
- All quadrupoles are equipped with connectors for the power supplies
- "Plug and play" system can be operated by nearly everyone
- Faster change of quadrupole during the measurement and also possible at any time
- Measurement will start end of September





SUMMARY

- Beam-based alignment used to determine offset between beam position monitors and quadrupole centers
- Optimal position inside 12 quadrupoles could be determined at COSY
- Now known beam position monitor offset can be corrected for to have a better orbit
- There are 56 quadrupoles in total in COSY to be measured
- Plan to measure all the quadrupoles in the ring starting end of September

