BEAM BASED ALIGNMENT Beam Based Alignment tests at COSY

March 19, 2018 | Tim Wagner, on behalf of the JEDI Collaboration |







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COSY Cooler Syncrotron

- Circumference: 184 m
- Provides polarized protons and deuterons
- Maximum momentum: 3.65 GeV/c
- Intensity: 10⁹ to 10¹⁰ particles
- Electron cooling
- Spin manipulators

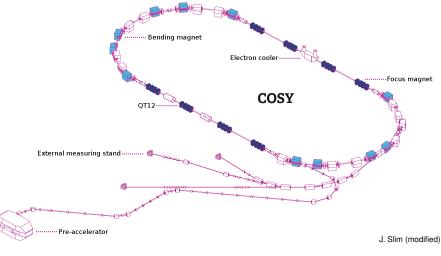


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Slide 1

COSY Cooler Syncrotron

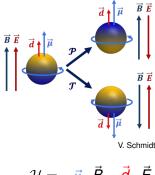




ELECTRIC DIPOLE MOMENT (EDM)

- Permanent EDMs of light hadrons are *T*- and *P*-violating
- \mathcal{CPT} theorem $\rightarrow \mathcal{CP}$ violation
- Measure EDMs of charged particles in storage rings
- $d_{Neutron} < 3 \times 10^{-26} \, \mathrm{e} \cdot \mathrm{cm}$
- $d_{Proton} < 5 \times 10^{-24} \, \mathrm{e} \cdot \mathrm{cm}$
- d_{Deuteron} = ?

$$\vec{d} = \eta \cdot \frac{q}{2mc}\vec{S}$$



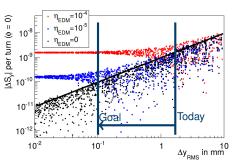
 $\mathcal{H} = -\vec{\mu} \cdot \vec{B} - \vec{d} \cdot \vec{E}$ $\mathcal{P} : \mathcal{H} = -\vec{\mu} \cdot \vec{B} + \vec{d} \cdot \vec{E}$ $\mathcal{T} : \mathcal{H} = -\vec{\mu} \cdot \vec{B} + \vec{d} \cdot \vec{E}$



Slide 3

Why is it needed?

- For an EDM measurement the orbit has to be as good as possible
- Orbit RMS should be lower than 100 µm
 → Orbit Control
- Orbit Control corrects the beam to the BPM zero position



M.Rosenthal, PhD Thesis (modified)

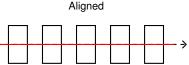
- Goal is to go central through all magnets (i.e. quadrupoles)
- Thus BPM to quadrupole offset has to be known
 → Beam Based Alignment

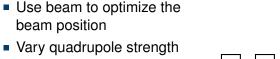


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- Observe orbit change
- Try to minimize the orbit change





BEAM BASED ALIGNMENT

How does it work?



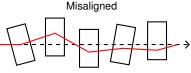
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BEAM BASED ALIGNMENT How does it work?

- Use beam to optimize the beam position
- Vary quadrupole strength
- Observe orbit change
- Try to minimize the orbit change





Slide 5

How does it work?

How does the orbit change when varying the quadrupole strength?

$$\Delta x(s) = \left(\frac{\Delta k x(\bar{s})I}{B\rho}\right) \left(\frac{1}{1 - k \frac{I\beta(\bar{s})}{2B\rho \tan \pi \nu}}\right)$$
$$\times \frac{\sqrt{\beta(s)}\sqrt{\beta(\bar{s})}}{2\sin \pi \nu} \cos(\phi(s) - \phi(\bar{s}) - \pi \nu)$$

 Not possible to calculate x(s) due to lack of precise knowledge of all other parameters



How does it work?

Use the following merit function

$$egin{aligned} f &= rac{1}{N_{ ext{BPM}}} \sum_{i=1}^{N_{ ext{BPM}}} (x_i (+\Delta k) - x_i (-\Delta k))^2 \ &\quad f \propto (\Delta x)^2 \propto (x(ar{s}))^2 \end{aligned}$$

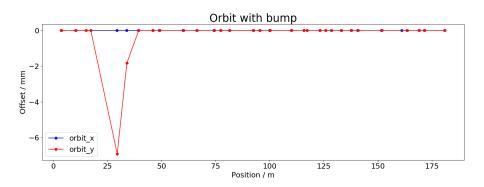
By finding the minimum the optimal beam position can be found



- Simulation of COSY done with MAD-X
- Option 1: Generate a bump inside the quadrupole
- Option 2: Move the quadrupole
- Vary the quadrupole strength
- Obseve the effect on the orbit
- Calculate the optimal position

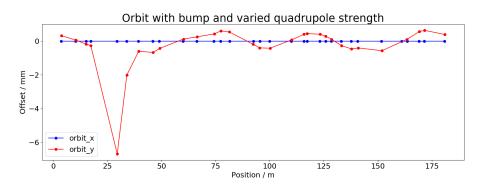


Example Bump





Example Bump

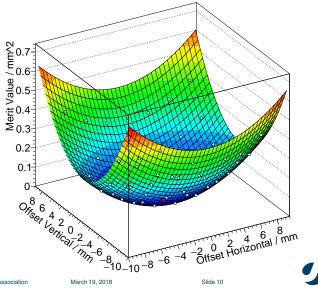




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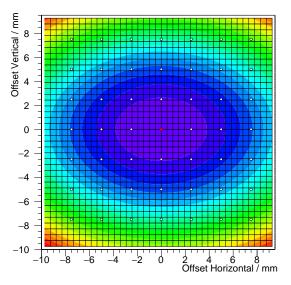
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Option 1 - Apply Bump





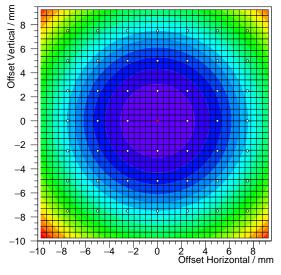
SIMULATION Option 1 - Apply Bump



- Asymmetric due to imperfect bumps
- Different slopes of the beam for horizontal and vertical direction



Option 2 - Move Quadrupole

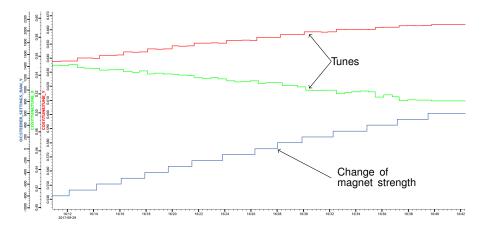




- Quadrupoles are powered in families of four
- On the poles of quadrupole QT12 the additional coils of the steerer BLW04 were recabled to work as a quadrupole

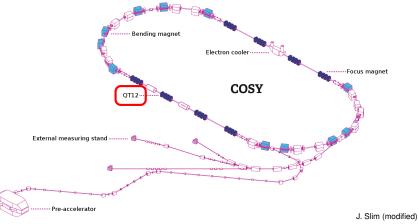


Quadrupole behavior





Location of QT12



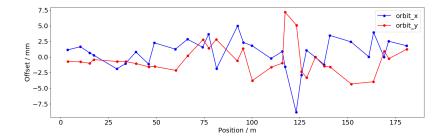
COSY scetch with position of quadrupole QT12 indicated



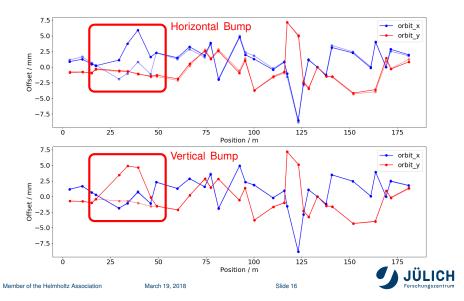
- Quadrupoles are powered in families of four
- On the poles of quadrupole QT12 the additional coils of the steerer BLW04 were recabled to work as a quadrupole
- Effectively the strength of quadrupole QT12 can be varied
- Local bumps applied at the position of the quadrupole
- Measured effect on orbit upon varying the quadrupole strength



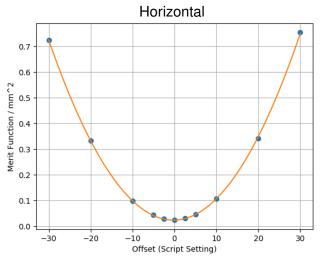
MEASUREMENT Orbit





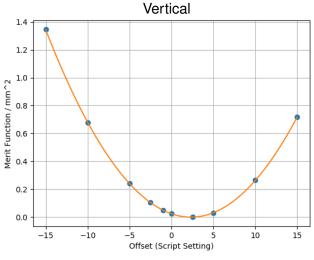


RESULTS



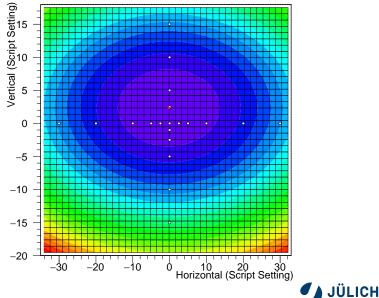


RESULTS





RESULTS



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	Optimal Position	in mm
Horizontal	$-0.255{\pm}0.028$	$-1.98{\pm}0.01$
Vertical	$2.329{\pm}0.011$	1.15±0.01

- Optimal position given in script setting
- The values in mm are the BPM 6 readings nearby



SUMMARY & OUTLOOK

- Beam based alignment works
- The change of the magnet strength with additional coils works
- Optimal beam position inside the quadrupole could be determined to be $(-1.98\pm0.01)\,\text{mm}$ horizontally and $(1.15\pm0.01)\,\text{mm}$ vertically
- Additional quadrupole magnets need to be changed to be individually controlled
- Measurement all along the ring to obtain quadrupole to BPM offsets





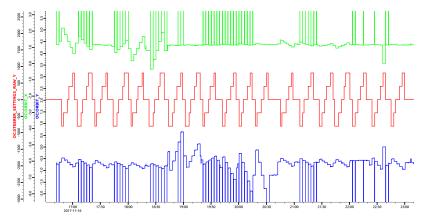






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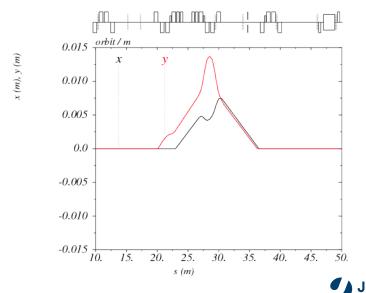
MEASUREMENT SCREENSHOT



Screenshot of the measurement. In red the change of the magnet strength is shown and in green and blue an example for a bpm reading. For each scan a different beam position was used.

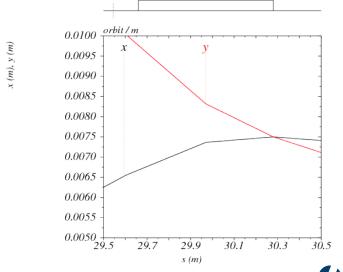


SIMULATION: BUMP



Forschung

SIMULATION: BUMP





Derivation of formula for orbit change

$$\Delta x(s) = \left(\frac{\Delta k \cdot x(\bar{s})I}{B\rho}\right) \left(\frac{1}{1 - k \frac{I\beta(\bar{s})}{2B\rho \tan \pi \nu}}\right) \frac{\sqrt{\beta(s)}\sqrt{\beta(\bar{s})}}{2\sin \pi \nu} \cos(\phi(s) - \phi(\bar{s}) - \pi \nu)$$

- Δx = orbit change
- s = measurement position
- \bar{s} = position of quadrupole
- Δk = change of quadrupole strength
- x(s) = position of beam inside the quadrupole

•
$$\beta$$
 = beta function

•
$$\phi$$
 = betatron phase

•
$$k = quadrupole strength$$

*B*_ρ = magnetic rigidity of the beam



Derivation of formula for orbit change

• Start with effect of a dipole kick θ on the orbit.

$$\Delta x(s) = heta imes rac{\sqrt{eta(s)}\sqrt{eta(ar{s})}}{2\sin\pi
u}\cos(\phi(s)-\phi(ar{s})-\pi
u) \ heta = rac{\Delta Bl}{B
ho}$$

- To first order a beam offset inside a quadrupole sees a change in quadrupole strength as a dipole kick.
- The change of the tune, beta function and betaton phase are effects of second order and can be neglected.



Derivation of formula for orbit change

• Quadrupole magnetic field is B = kx, thus

 $\Delta B = (k + \Delta k)(x + \Delta x) - kx = \Delta kx + \Delta xk + \mathcal{O}(\Delta k \Delta x)$

• Combine the equations with $\bar{s} = s$ to get

$$\Delta x = \frac{(\Delta kx + \Delta xk)I}{B\rho} \frac{\beta}{2\sin \pi\nu} \cos \pi\nu$$

• and solve for Δx .

$$\Delta x = \Delta kx \frac{\frac{\beta l}{2B\rho \tan \pi \nu}}{1 - \frac{\beta l}{2B\rho \tan \pi \nu}}$$



Derivation of formula for orbit change

• With that calculate ΔB

$$\Delta B = \Delta kx \frac{1}{1 - k \frac{\beta I}{2B\rho \tan \pi \nu}}$$

• and insert that into the equation for θ and $\Delta x(s)$.

$$\Delta X(\boldsymbol{s}) = \left(\frac{\Delta k \cdot x(\bar{\boldsymbol{s}})l}{B\rho}\right) \left(\frac{1}{1 - k\frac{l\beta(\bar{\boldsymbol{s}})}{2B\rho \tan \pi\nu}}\right) \frac{\sqrt{\beta(\boldsymbol{s})}\sqrt{\beta(\bar{\boldsymbol{s}})}}{2\sin \pi\nu} \operatorname{Cos}(\phi(\boldsymbol{s}) - \phi(\bar{\boldsymbol{s}}) - \pi\nu)$$

